

Tsunamis

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Main Properties of Tsunamis

- Gravity waves with periods between ≈ 100 s and 10,000 s
- Propagate at high velocities in deep water
- Mainly horizontal particle motion of the entire water column down to the ocean floor



Rather small dissipation of energy



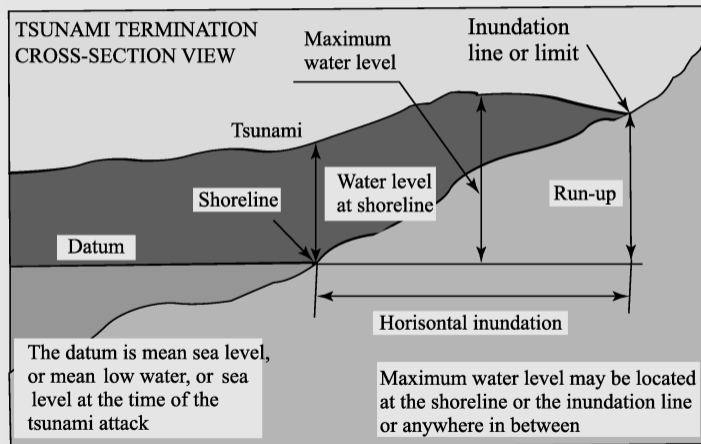
Travel over large distances

- Wave height increases with decreasing ocean depth



Large wave heights at the coast

Basic Terms

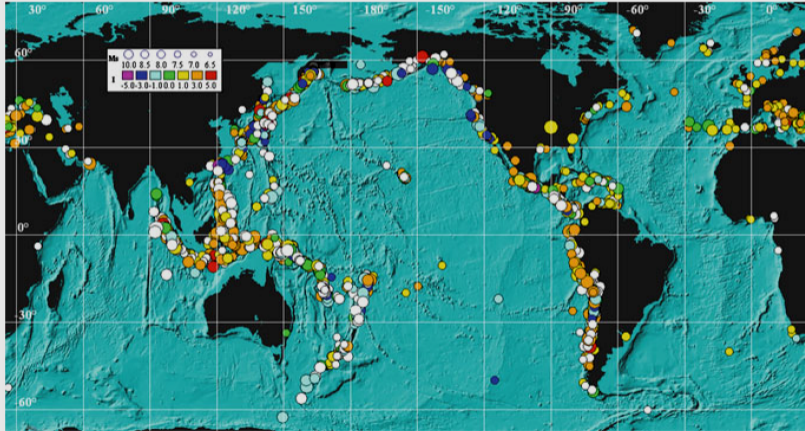


Source: Levin & Nosov, Physics of Tsunamis

Main Sources of Tsunamis

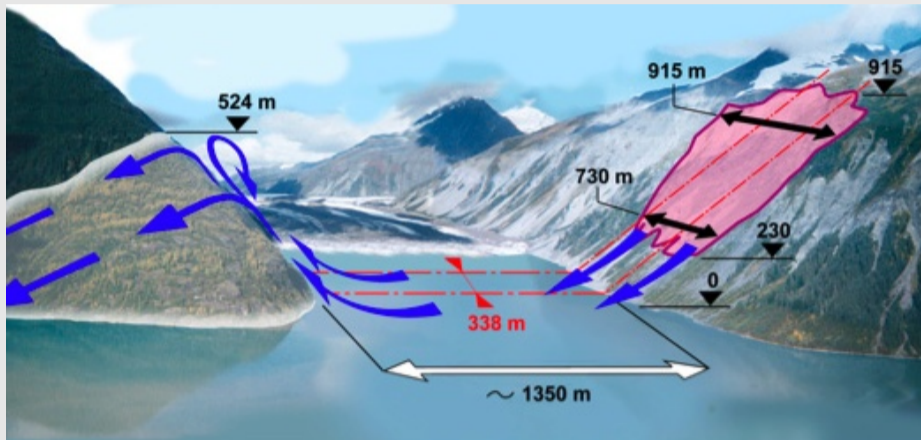
- Earthquakes (more than 90 % of all tsunamis)
- Landslides
- Volcanic eruptions
- Meteorite impact (rare)

Known Tsunami Sources from 2000 B.C. to 2014



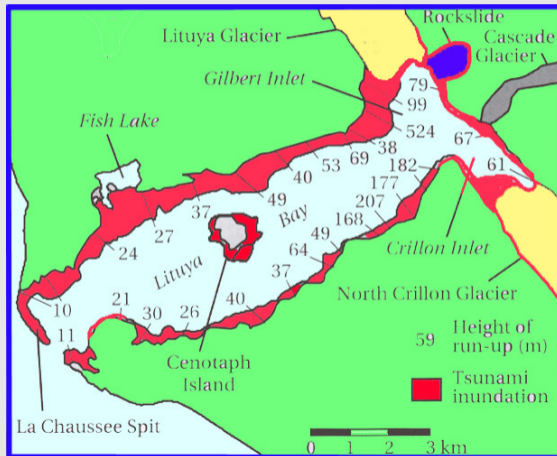
Source: Levin & Nosov, Physics of Tsunamis

The Tallest Tsunami Known so far: Lituya Bay, 1958



Source: Pararas-Carayannis, The Mega-Tsunami of July 9, 1958 in Lituya Bay, Alaska

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The Tallest Tsunamis 2000–2014

Date	Location	M_W	H_{\max} [m]	Death toll
11.03.2011	Japan	9.0	56	18,482
24.12.2004	Indonesia, Sumatra	9.1	51	227,899
27.02.2010	Chile	8.8	29	156
29.09.2009	Samoa	8.1	22	192
15.11.2006	Russia, Kuril Islands	8.3	22	0
17.07.2006	Indonesia, South of Java	7.7	21	802
25.10.2010	Indonesia, Sumatra	7.8	17	431

Types of Intensity and Magnitude Scales

Type	Adressed property	Examples
intensity	effect on humans and infrastructure	Sieberg-Ambraseys scale Papadopoulos-Imamura scale
	wave height at the coast	Imamura-lida scale Soloviev-Imamura scale
magnitude	strength at the source of the tsunami	Abe-Hatori scale Murty-Loomis scale

The Sieberg-Ambraseys Scale

- Originally introduced by A. H. Sieberg (1927)
- Modified by N. N. Ambraseys (1962)
- Six-point scale from 1 = very light to 6 = disastrous

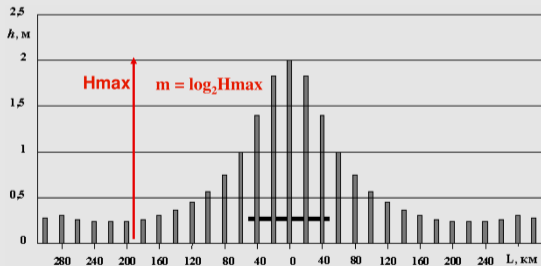
The Papadopoulos-Imamura Scale

- Introduced by G. A. Papadopoulos and F. Imamura (2001)
- 12-point scale similar to the Mercalli scale for earthquakes from I = not felt to XII = destructive

The Imamura-Iida Scale

- Introduced by A. Imamura (1942); modified by K. Iida (1956)
- Defined as

$$m = \log_2 H_{\max} \quad (1)$$



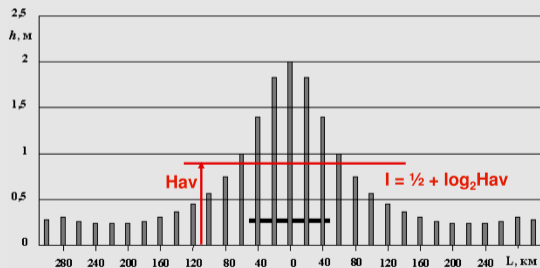
Source: Gusiakov, Tsunami Quantification

- Originally termed magnitude

The Soloviev-Imamura Scale

- Modification of the Imamura-Iida scale by S. Soloviev (1972)
- Defined as

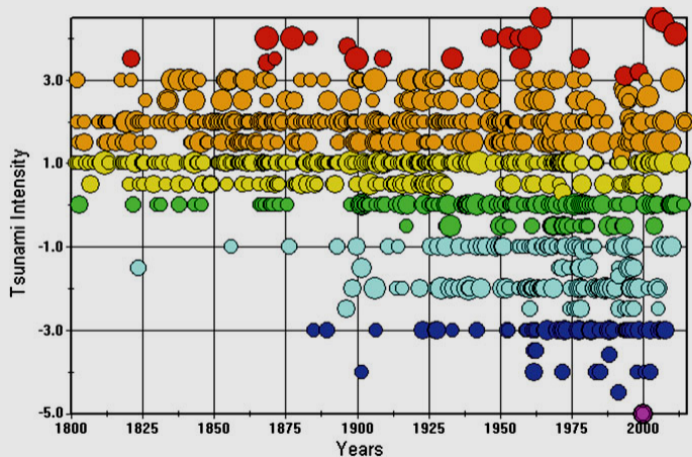
$$I = \frac{1}{2} + \log_2 H_{av} \quad (2)$$



Source: Gusiakov, Tsunami Quantification

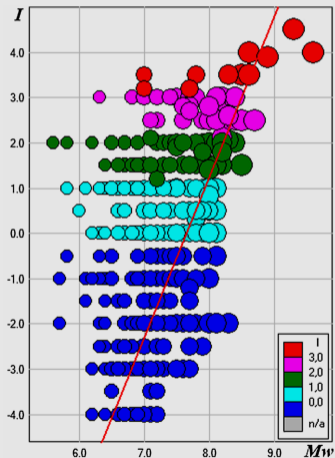
- Widely used in tsunami catalogs

The Soloviev-Imamura Scale



Source: Levin & Nosov, Physics of Tsunamis

The Soloviev-Imamura Scale



Source: Gusiakov, Pure Appl. Geophys., 2015

The Abe-Hatori Scale

- Introduced in 1979 by K. Abe
- First attempt to define a tsunami magnitude taking into account the distance from the source:

$$M_t = a \log_{10} H_{\max} + b \log_{10} \Delta + D \quad (3)$$

where

H_{\max} = maximum wave amplitude at the coast

Δ = distance

a, b, D = constants

The Murty-Loomis Scale

- Introduced in 1980 by T. S. Murty and H. G. Loomis.
- Based on the total potential energy E (in J here, originally in ergs):

$$ML = 2(\log_{10} E - 12) \quad (4)$$

- Well-defined and theoretically a good measure of the strength of a tsunami, but suffers from the problem of determining the total potential energy.

Starting Point

Elastic medium with $\mu = 0$:

$$\boldsymbol{\sigma} = \lambda \epsilon_v \mathbf{1} = -p \mathbf{1} \quad (5)$$

where

$$p = -\lambda \epsilon_v = -\lambda \operatorname{div}(\vec{u}) \quad (6)$$

is called **pressure**.

- Mechanically equivalent to a compressible, inviscid fluid.
- Theory is only valid for small displacement.



Kinematically not appropriate for describing fluids in general, but for waves with small amplitudes.

Types of Waves in Fluids

P body waves: sound wave; slowness

$$s = \frac{1}{v_p} = \sqrt{\frac{\rho}{\lambda}} \quad (7)$$

P interface waves:

- Prograde particle movement on horizontal elliptical orbits
- Amplitude decreases with depth; depth of penetration

$$d = \frac{1}{\omega \sqrt{s_1^2 - |\vec{s}|^2}} = \frac{L}{2\pi \sqrt{1 - \frac{|\vec{s}|^2}{s_1^2}}} \quad (8)$$

with $L = \frac{2\pi}{\omega s_1}$

P Interface Waves in Fluids



Particle displacement:

$$\vec{u}(\vec{x}, t) = e^{i\omega(t - \vec{s} \cdot \vec{x})} \vec{a} \quad (9)$$

$$= e^{i\omega(t - s_1 x_1)} e^{\pm \frac{x_3}{d}} \vec{a} \quad (10)$$

with

$$\frac{u_3(\vec{x}, t)}{u_1(\vec{x}, t)} = \frac{a_3}{a_1} = \frac{s_3}{s_1} \quad (11)$$

$$= \pm i \sqrt{1 - \frac{|\vec{s}|^2}{s_1^2}} = \pm \frac{i}{\omega s_1 d} \quad (12)$$

where only the + sign makes sense in the lower halfspace

P Interface Waves in Fluids

Pressure:

$$p(\vec{x}, t) = -\lambda \operatorname{div}(\vec{u}(\vec{x}, t)) = \boxed{} e^{i\omega(t-\vec{s}\cdot\vec{x})} \quad (13)$$

From Eq. 12:

$$\vec{s} \cdot \vec{a} = s_1 a_1 + s_3 a_3 = s_1 a_1 \left(1 + \frac{s_3}{s_1} \frac{a_3}{a_1} \right) \quad (14)$$

$$= \frac{a_1 |\vec{s}|^2}{s_1} = a_1 \frac{\rho}{\lambda s_1} = \pm a_3 \frac{\rho \omega d}{i \lambda} \quad (15)$$



$$p(\vec{x}, t) = \pm \boxed{} e^{i\omega(t-\vec{s}\cdot\vec{x})} = \pm \boxed{} u_3(\vec{x}, t) \quad (16)$$

P Surface Waves in Fluids

No surface with $p(\vec{x}, t) = 0$ (or constant) at any time



P interface wave cannot be a surface wave.

P Surface Waves in Fluids With Gravity

Gravity causes additional hydrostatic pressure

$$p_{\text{hy}}(\vec{x}, t) = -\rho g(x_3 + u_3(\vec{x}, t)) \quad (17)$$



$$p(\vec{x}, t) = \pm \rho \omega^2 d u_3(\vec{x}, t) - \rho g(x_3 + u_3(\vec{x}, t)) \quad (18)$$

P Surface Waves in Fluids With Gravity

Free surface at $x_3 = 0$ ($p(x_1, x_2, 0, t) = 0$) is possible if

$$\omega^2 = \frac{g}{d} = \omega g \sqrt{s_1^2 - |\vec{s}|^2} \quad (19)$$

The Velocity of Propagation

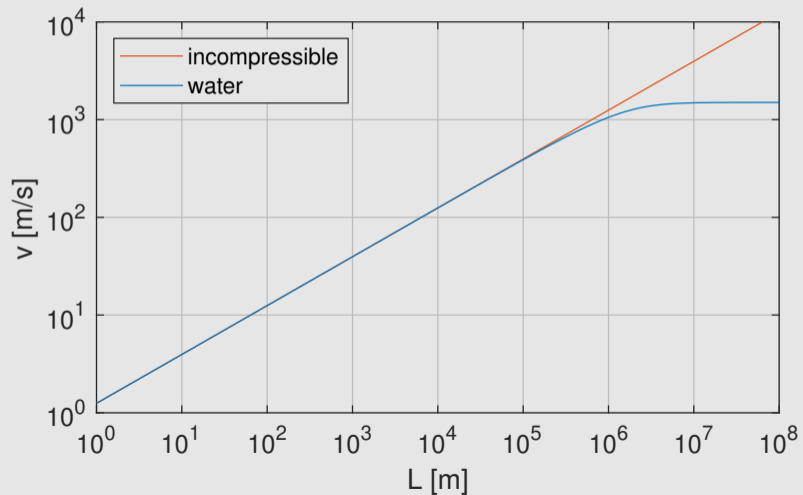
Slowness:

$$s_1^2 = |\vec{s}|^2 + \left(\frac{\omega}{g}\right)^2 \quad (20)$$

Expressed in terms of the wavelength $L = \frac{2\pi}{\omega s_1}$:

$$s_1^2 = \frac{|\vec{s}|^2}{2} + \sqrt{\left(\frac{|\vec{s}|^2}{2}\right)^2 + \left(\frac{2\pi}{gL}\right)^2} \quad (21)$$

Velocity of Propagation



Boundary Condition at the Ocean Floor

Consider domain $-H \leq x_3 \leq 0$ with a given ocean depth H .



Solution must meet the condition $u_3(x_1, x_2, -H, t) = 0$.

Superposition of the solutions with $+$ and $-$ signs

$$u_3(\vec{x}, t) = \square \left(a_3 e^{i\omega(t-s_1x_1)} e^{\frac{x_3}{d}} \right) + \square \left(a_3 e^{i\omega(t-s_1x_1)} e^{-\frac{x_3}{d}} \right) \quad (22)$$

$$= a_3 e^{i\omega(t-s_1x_1)} \left(\square \right) \quad (23)$$

$$= 2a_3 e^{i\omega(t-s_1x_1)} \square \left(\frac{x_3 + H}{d} \right) \quad (24)$$

satisfies the boundary condition at $x_3 = -H$.

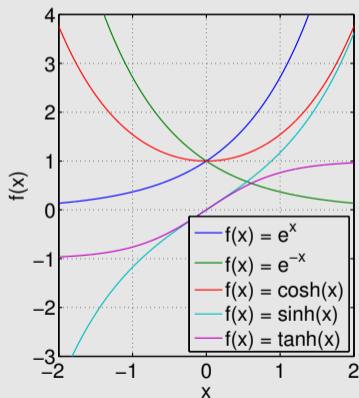
The Hyperbolic Cosine, Sine and Tangent Functions

$$\cosh(x) = \frac{e^x + e^{-x}}{2} \quad (25)$$

$$\sinh(x) = \frac{e^x - e^{-x}}{2} \quad (26)$$

$$\tanh(x) = \frac{\sinh(x)}{\cosh(x)} \quad (27)$$

$$= \frac{e^x - e^{-x}}{e^x + e^{-x}} \quad (28)$$



Vertical Particle Displacement

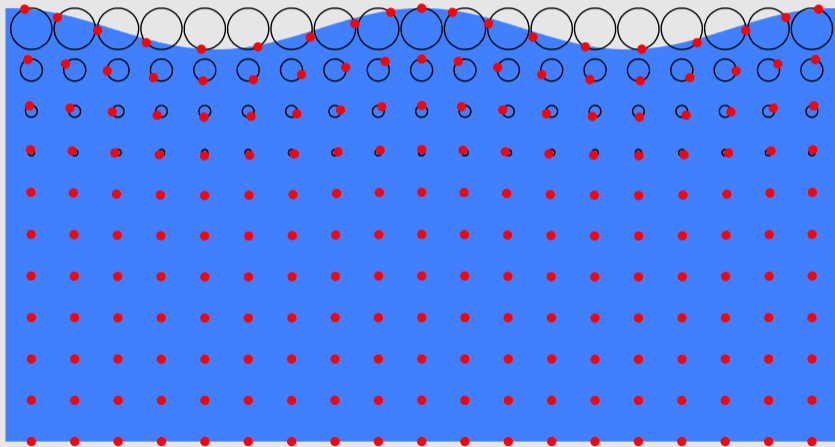
Wave height

$$h = u_3(\vec{0}, 0) = 2a_3 \sinh\left(\frac{H}{d}\right) \quad (29)$$

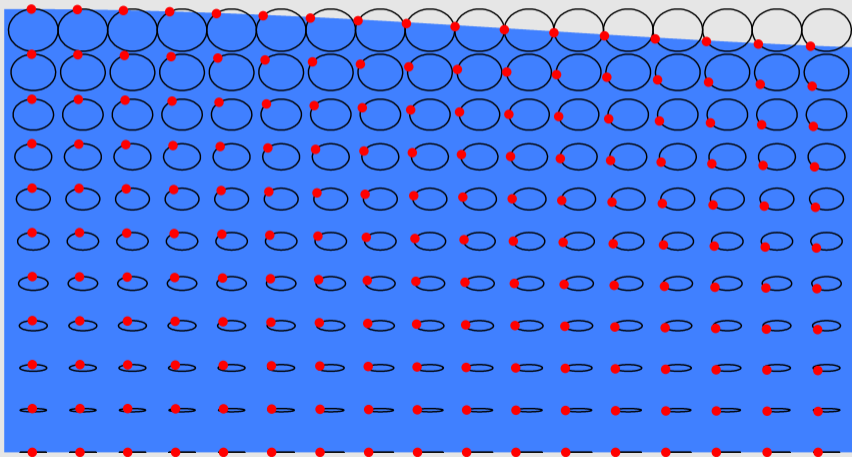


$$u_3(\vec{x}, t) = h e^{i\omega(t-s_1x_1)} \frac{\sinh\left(\frac{x_3+H}{d}\right)}{\sinh\left(\frac{H}{d}\right)} \quad (30)$$

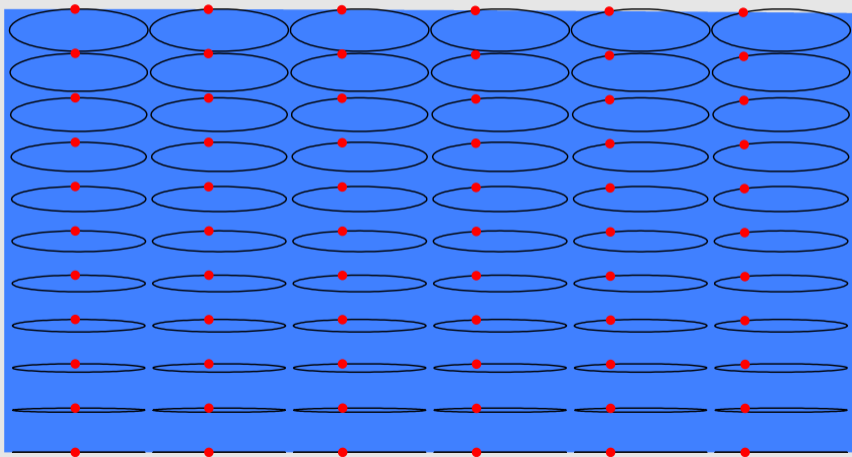
Particle Orbits for $L/H = 1$ (incompressible)



Particle Orbits for $L/H = 5$ (incompressible)



Particle Orbits for $L/H = 20$ (incompressible)



The Velocity of Propagation

Pressure (Eq. 18) for the superposed solution (Eq. 24):

$$p(\vec{x}, t) = \rho\omega^2 d \left(a_3 e^{i\omega(t-s_1x_1)} \left(e^{\frac{x_3+H}{d}} + e^{-\frac{x_3+H}{d}} \right) \right) \\ - \rho g \left(x_3 + \left(a_3 e^{i\omega(t-s_1x_1)} \left(e^{\frac{x_3+H}{d}} - e^{-\frac{x_3+H}{d}} \right) \right) \right) \quad (31)$$

$$= 2a_3\rho e^{i\omega(t-s_1x_1)} \left(\omega^2 d \cosh \left(\frac{x_3+H}{d} \right) - g \sinh \left(\frac{x_3+H}{d} \right) \right) \\ - \rho g x_3 \quad (32)$$

Free surface at $x_3 = 0$ ($p(x_1, x_2, 0, t) = 0$) is possible if

$$\omega^2 = \frac{g}{d} \tanh \left(\frac{H}{d} \right) = \omega g \sqrt{s_1^2 - |\vec{s}|^2} \tanh \left(\frac{H}{d} \right) \quad (33)$$

The Velocity of Propagation

Generalization of Eq. 21:

$$s_1^2 = \frac{|\vec{s}|^2}{2} + \sqrt{\left(\frac{|\vec{s}|^2}{2}\right)^2 + \left(\frac{2\pi}{gL \tanh\left(\frac{H}{d}\right)}\right)^2} \quad (34)$$

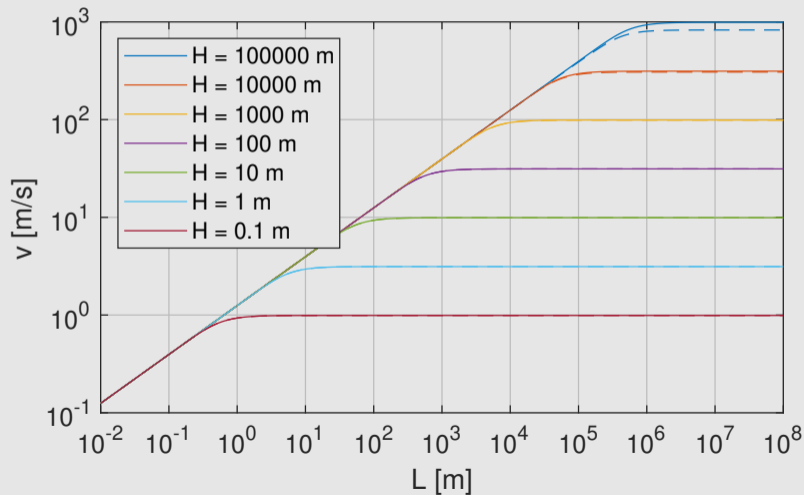
For incompressible fluids ($|\vec{s}| = 0$, $d = \frac{L}{2\pi}$):

$$s_1^2 = \frac{2\pi}{gL \tanh\left(\frac{2\pi H}{L}\right)} \quad (35)$$



$$v = \sqrt{\frac{gL}{2\pi} \tanh\left(\frac{2\pi H}{L}\right)} \quad (36)$$

The Velocity of Propagation



Regimes of Ocean Wave Propagation

Deep water regime: $\frac{d}{H} \leq \frac{1}{\pi} \Leftrightarrow \frac{L}{H} \leq 2$

- Particles move on almost circular orbits.
- Particle movement is practically limited to a depth less than one wavelength.
- Horizontal particle displacement at the ocean floor is less than 10% of the displacement at the surface.
- Velocity depends on the wavelength, but not on ocean depth:

$$v \approx \sqrt{\frac{gL}{2\pi}}, \quad (37)$$

- Strong dispersion

Regimes of Ocean Wave Propagation

Shallow water regime: $\frac{d}{H} \geq \frac{10}{\pi} \Leftrightarrow \frac{L}{H} \geq 20$

- Particles move on elliptical orbits.
- Horizontal particle movement persists down to the ocean floor; at the ocean floor more than 95 % of the displacement at the surface.
- Velocity only depends on ocean depth:

$$v \approx \sqrt{gH}$$

- No dispersion

Dispersion

Examples of tsunami wave dispersion in a 4000 m deep ocean (symmetric propagation to the left and to the right):

- bell-shaped (Gaussian) wave
- boxcar-shaped wave
- double boxcar-shaped wave
- step-like wave

The Fluid Pressure

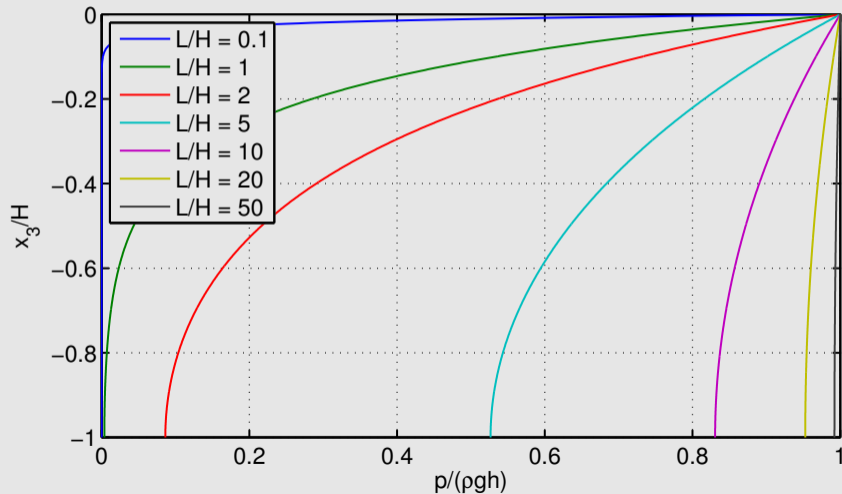
Variation in fluid pressure without hydrostatic pressure from Eqs. 32, 29, and 33:

$$p(\vec{x}, t) = 2a_3 \rho e^{i\omega(t-s_1 x_1)} \omega^2 d \cosh\left(\frac{x_3+H}{d}\right) \quad (38)$$

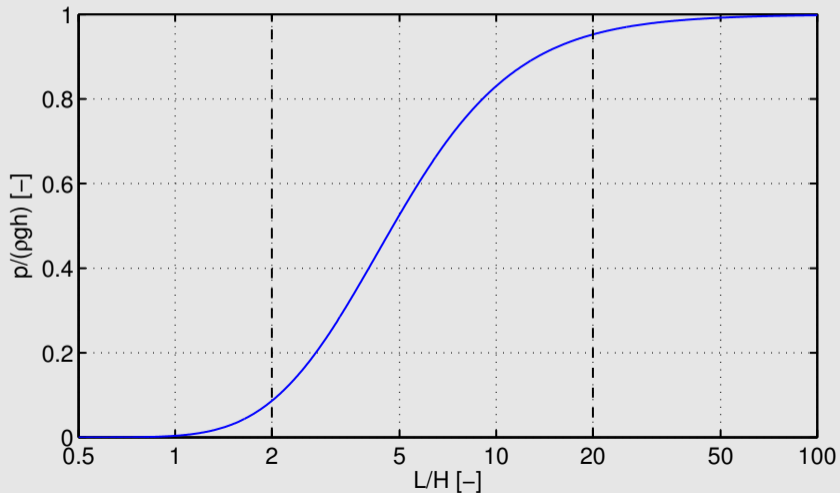
$$= \frac{h}{\sinh\left(\frac{H}{d}\right)} \rho e^{i\omega(t-s_1 x_1)} \frac{g}{d} \tanh\left(\frac{H}{d}\right) d \cosh\left(\frac{x_3+H}{d}\right) \quad (39)$$

$$= \rho g h e^{i\omega(t-s_1 x_1)} \frac{\cosh\left(\frac{x_3+H}{d}\right)}{\cosh\left(\frac{H}{d}\right)} \quad (40)$$

The Fluid Pressure



Variation in Pressure at the Ocean Floor



Variation in Pressure at the Ocean Floor

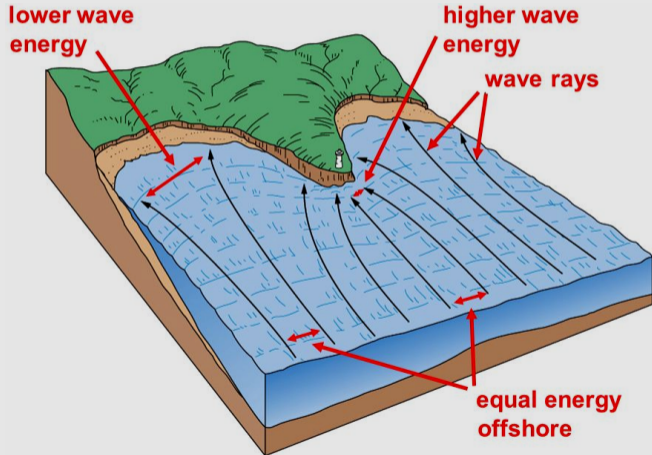
Deep water regime ($\frac{L}{H} \leq 2$): < 10 % of the near-surface variation at the ocean floor.

Shallow water regime ($\frac{L}{H} \geq 20$): > 95 % of the near-surface variation at the ocean floor.



Most important component of tsunami warning systems beyond earthquake registration.

Wave Shoaling



Source: Carpenter, Ocean Waves

Ray Theory

Extensions towards the harmonic plane wave approach:

- Retarded time $\tau = t - \psi(x_1, x_2)$ instead of $\tau = t - s_1 x_1$ with a general phase function $\psi(x_1, x_2)$



Propagation in direction of $\nabla\psi(x_1, x_2)$ with local slowness $|\nabla\psi(x_1, x_2)|$

- Spatially variable wave height $h(x_1, x_2)$
- Vertical particle displacement in analogy to Eq. 30,

$$u_3(\vec{x}, t) = h e^{i\omega(t-\psi(x_1, x_2))} \frac{\sinh\left(\frac{x_3+H}{d}\right)}{\sinh\left(\frac{H}{d}\right)} \quad (41)$$

so that $u_3 = 0$ at the ocean floor.

Ray Theory

Calculations in analogy the eikonal equation for seismic waves.



Terms $\sim \omega^2$:

- Horizontal particle displacement only in direction of propagation
- Velocity of propagation according to Eq. 36

Terms $\sim \omega$:

$$\operatorname{div}(\vec{q}) = 0 \quad (42)$$

with the energy flux density

$$\vec{q} = \frac{1}{2} \rho g h^2 \vec{v} \quad (43)$$